# EECS 298 - RTOS survey

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# RTOS survey

- eCos
  - -RedHat(Open Source)
- VxWorks
  - Windriver (Commercial)
- QNX Neutrino
  - -QNX Software (Commercial)

#### Architecture

- eCos
  - Kernel Based (Optional)
    - Scheduling and synchronization, interrupt and exception handling, counters, clocks, alarms, timers.
    - · OS components can be customized
- VxWorks
  - Kernel Based
    - Individual scheduler, memory management, intertask, synchronization, messaging, timers, interrupt servicing, and device I/O, interface
    - · OS components can be customized
  - All tasks including OS run in supervisor mode
    - · Possible corruption of internal OS structures
- ONX Neutrino
  - Microkernel Based
    - Minimal services used by a team of cooperating processes, which in turn provide the higher-level OS functionality.
    - Every driver, application, protocol stack, and file system runs outside the microkernel, in the safety of memory-protected user space
  - Clear delineation between the operating system and the application
    - · Completely isolates the user applications from the OS.

#### Scheduling

- eCos
  - Multilevel Queue Scheduler (0 to 31)
    - Multi thread execution
  - Bitmap Scheduler (0 to 31)
    - Single thread execution
- VxWorks / QNX Neutrino
  - Fully Preemptive Priority-based Scheduler(256)
    - First-In-First-Out (FIFO) and/or Round Robin.
- QNX Neutrino
  - Sporadic Scheduling
    - Allows application threads with sporadic CPU utilization requirements to allocate execution budgets for themselves.

### Intertask/interprocess communications

- eCos
  - Synchronization
    - Mutex lock, Counting Semaphores, Flags, Spinlocks
  - InterTask Communication
    - · Mailboxes.
- VxWorks
  - Synchronization
    - · Semaphores(binary, counting, and mutual-exclusion)
  - InterTask Communication
    - Message queues(Priority or FIFO)
- QNX Neutrino
  - Synchronization
    - Mutex lock.
  - InterTask Communication
    - · Message passing forms a virtual "software bus"

### **RTOS Selection**

- Based on Paper from Canadian Space Agency
- 48 Different RTOS Evaluated
- Selection Criteria(elimination)
  - Platform and/or Kernel Footprint
    - (For Workstations, DSP, MicroControllers)
  - Lack of Hard Real Time Capability
  - Limited Process Support & OS Dependencies

### Eliminated Candiates

RTOS Name	Vendor	Reason for elimination		
BeOS™	Be inc.	Platform and/or size kernel footprint		
Blue Cat™	LynuxWorks	Lack of determinism and/or limited real-time capabilities		
Chorus OS™	Sun Microsystems	Platform and/or size of kernel footprint		
Embedix Real-Time™	Lineo	Platform and/or size of kernel footprint		
EPOC™	Symbian	Platform and/or size of kernel footprint		
eRTOS™	JK Microsystems	Only one supported processor		
ETS™	Phar Lap (VenturCom)	Other OS dependency		
EYRX™	Eyring Corp	Only one supported processor		
GEOs™	Geoworks	Other OS dependency		
Inferno™	Lucent Tech (Vita Nuova)	Platform and/or size of kernel footprint		
InTime™	Ten Asys	Other OS dependency		
Jbed™	Esmertec	Other OS dependency		
NetBSD™		Lack of determinism and/or limited real-time capabilities		
On Core OS™	On Core Systems	Other OS dependency		
On Time RTOS-32™	On Time Software	Other OS dependency		
PDOS™	Eyring	Limited processor support		
PSOS™	VxWorks, previously Integrated Systems	Still available but being phased out		
QNX 4™	QNX	Other product from same vendor better choice		
Real-Time Architect / SSX5™	LiveDevices Ltd	Platform and/or size of kernel footprint		
RT Linux™	FMSLabs	Other OS dependency		
RTX™	VenturCom	Other OS dependency		
RTXC™	Lineo, previously Embedded Power Corp	No longer available		
Run HyperPanel OS™	HyperPannel	Other OS dependency		
Thread X™	Green Hills Software	Other product from same vendor better choice		
TronTask™	US software	Other product from same vendor better choice		
Uclinux™	Lineo	Lack of determinism and/or limited real-time capabilities		
VelOSity™	Green Hills Software	No longer available		
Virtuoso™	Wind River (previously Eonic Systems)	Platform and/or size of kernel footprint		

## Remaining Candiates

RTOS Name	Vendor	
$AMX^{TM}$	Kadak	
C Executive™	JMI Software Systems	
CMX™	CMX Systems	
Cortex™	Artesys	
Delta OS™	CoreTek Systems	
E COS™	Cygnus Solutions (Red Hat)	
Emb OS™	Segger Microcontroller Systeme GmbH	
Integrity™	Green Hills Software	
Lynx OS™	Lynx Real time systems	
Nucleus Plus™	Accelerated Technology Incorporated	
OS-9™	Microware system corp	
OSE™	OSE (Enea)	
Precise/MQX™	Precise Software	
QNX/Neutrino™	QNX	
RTEMS™	On-Line Applications Research Corporation	
SuperTask™	US software	
TTPos™	TTTech	
UC/OS-II™	Micrium, Inc	
VRTX™	Mentor Graphics	
Vx Works™	Wind River systems	

### Evaluation Criteria & Associated Weights

Category Name	W,	Criterion	Wi	W <sub>i</sub> x W <sub>i</sub>
Kernel	13 %	Architecture	35 %	5 %
		Multi-process support	15 %	2 %
		Multi-processor support	25 %	3 %
		Fault tolerance	25 %	3 %
Scheduling	20 %	Algorithm	40 %	8 %
		Priority assignment mechanism	20 %	4 %
		Time to release task, independent from list length*	40 %	8 %
Process/Thread/Task	12 %	Number of priority levels	26 %	3.12 %
model		Priority inversion protection	18 %	2.16 %
		Task States	10 %	1.2 %
		Max number of tasks	18 %	2.16 %
		Task switching latency	18 %	2.16 %
		Dynamic priority changing	10 %	1.2 %
Memory	10 %	Min and max RAM space per task	20 %	2 %
		Min and max ROM space	20 %	2 %
		Max addressable memory space per task	20 %	2 %
		Memory protection support	20 %	2 %
		Dynamic allocation support	10 %	1 %
		Virtual memory support	8 %	0.08 %
		Memory compaction	2 %	0.2 %
Interrupt and	8 %	Preemptable ISRs	30 %	2.4 %
Exception Handling	1	Worst case interrupt handling time	30 %	2.4 %
		ISR model or levels	20 %	16%
		Modifiability of interrupt vector table	20 %	1.6 %
Application	7 %	Library compliance	4 %	0.28 %
Programming		Precise absolute clock	10 %	0.7 %
Interface		External clock support	10 %	0.7 %
		Synchronization and exclusion primitives	18 %	1.26 %
		Communication and message passing	18 %	1.26 %
		Network protocols	10 %	0.7 %
		Certifications	10 %	0.7 %
		I/O support	10 %	0.7 %
		File systems	10 %	0.7 %
Development	15 %	Development methodology	20 %	3 %
Information		RTOS supplied as source or object code	15 %	2.25 %
		Supported compiler	20 %	3 %
		Supported processors	30 %	4.5 %
	l	Supported development languages	15 %	2.25 %
Commercial	15 %	Cost	30 %	4.5 %
Information		Royalty fees	10 %	1.5 %
		Years on market (i.e. product maturity)	20 %	3 %
		Used in time critical applications	20 %	3 %
	l	Support type and cost	20 %	3 %

# **Evaluation Results**

QNX/Neutrino™	1st	
OS-9™	151	
Precise/MQX™	2nd	
OSE™		
Delta OS™	3rd	
RTEMS™		
Lynx OS™		
Integrity™		
VxWorks™		
Nucleus Plus™		
VRTX™		
TTPos™	4th	
C Executive™	701	
Emb OS™		
CMX™		
ECOS™	5th	
uC/OS-II™		
SuperTask™	5111	
AMX™		
Cortex™	6th	