Task

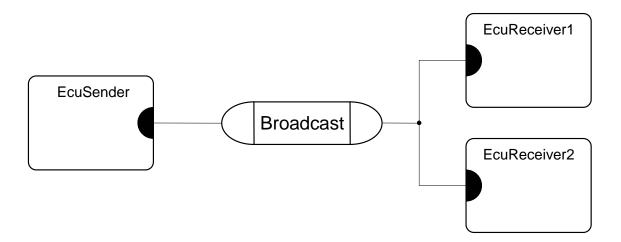
- Communication refinement of chosen ECU
 - Transaction Level Model (TLM)
 - Bus Functional Model (BFM)

Components

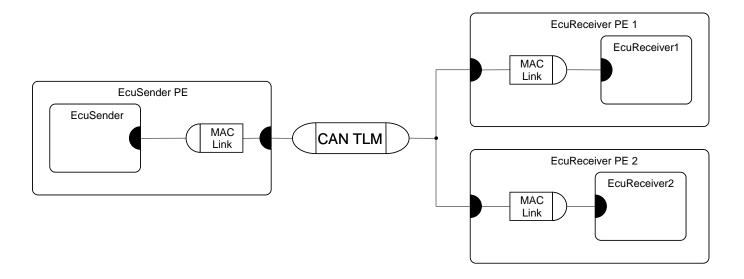
- Controller Area Network (CAN) Bus
 - provided SpecC models
 - TLM (file canEcu_tlm.sc)
 - BFM (file canEcu_bfm.sc)
 - see file /home/eecs298w06/canEcu.tar.gz on server epsilon.eecs.uci.edu

- Controller Area Network (CAN) Bus
 - Properties
 - Standard bus used in automotive industry (Bosch GmbH)
 - Serial, multi-master, broadcast communication protocol
 - Collision-avoidance arbitration (fixed priorities)
 - Built-in synchronization and error detection
 - Single wire protocol (pull-down mechanism)
 - Modeling in SpecC
 - G. Schirner, R. Dömer:
 "Abstract Communication Modeling:
 A Case Study Using the CAN Automotive Bus",
 IESS, August 2005.

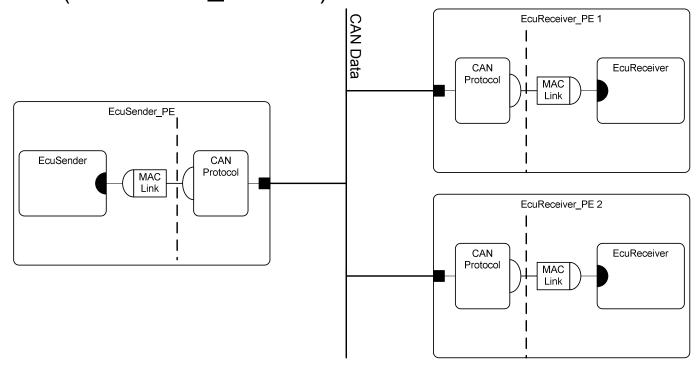
- Controller Area Network (CAN) Bus
 - Example
 - Abstract communication model (specification model)



- Controller Area Network (CAN) Bus
 - Example
 - Transaction level model (file canEcu_tlm.sc)



- Controller Area Network (CAN) Bus
 - Example
 - Bus-functional model (file canEcu_bfm.sc)



Deliverables

- Documentation
 - Schematic view of refined ECU models
 - Brief (!) description of functionality (in English)
 - e.g. FloorDoor_TLM.pdf, FloorDoor_BFM.pdf
- Refined ECU models in proper test bench
 - SpecC source code
 - e.g. FloorDoor_TLM.sc, FloorDoor_BFM.sc
- Successful simulation run
 - e.g. FloorDoor_TLM.log, FloorDoor_BFM.log

Due

- March 8, 2006, 11:59pm
- Email to doemer@uci.edu