

EECS 222A: System-on-Chip Description and Modeling Lecture 7

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Lecture 7: Overview

- Homework Assignment 4
 - Discussion
- Modeling of Hardware in SoC Design
 - Hardware Refinement
 - Register Transfer Level (RTL) Model
- RTL Modeling in SpecC
 - **bit**, **bit4** bit-vector types
 - **buffered** type modifier
 - **signal** type modifier
 - **fsmd** statement
- Homework Assignment 5
 - Creating behaviors from C code
 -

Homework Assignment 4

- Task
 - Creating behaviors in C code
 - initial system consists of
 - Test bench behavior Main
 - Stimulus behavior
 - Design Under Test (DUT)
 - Monitor behavior
 - we want to create more hierarchy in DUT
 - See posted detailed instructions!

Homework Assignment 4

- Deliverables
 - 1-paragraph description about the two tasks
 - How far did you get?
 - What were the problems?
 - How did you solve it?
 - Report the time stamps
 - How long did it take to do the tasks?
- Due
 - Week 7 (this week)

Modeling of Hardware in SoC Design

- Hardware Refinement (for each HW block)
 - Allocation of hardware components
 - Type and number of functional units
 - Type and number of storage units
 - Type and number of interconnecting busses
 - Scheduling
 - Representation of basic blocks as super-states
 - Scheduling of operations to clock cycles
 - Binding
 - Bind functional operations to functional units
 - Bind variables to storage units
 - Bind transfers to busses
 - Result:
 - Clock-cycle accurate HW model

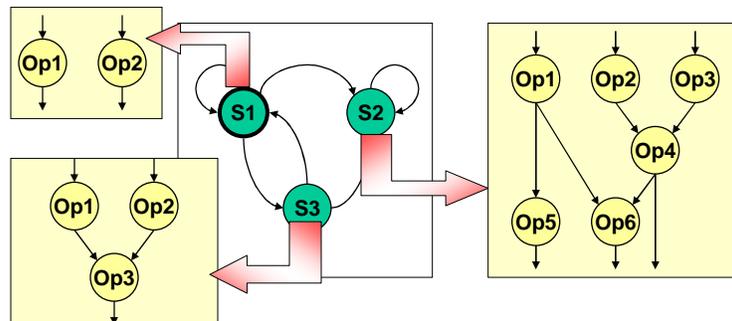
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Modeling of Hardware in SoC Design

- Hardware Modeling
 - FSMMD Model: Finite State Machine with Data
 - Combined model for control and computation
 - Implementation: controller plus datapath



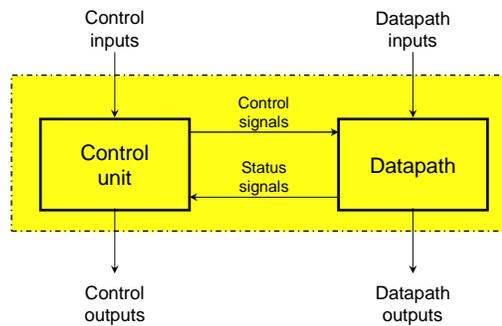
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Modeling of Hardware in SoC Design

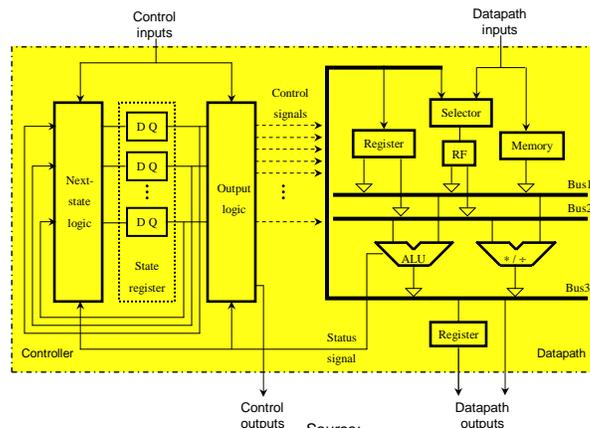
- Register Transfer Level (RTL) Modeling
 - Block diagram of generic RTL component (high level)



Source:
<http://www.eda.org/alc-cwg/cwg-open.pdf>

Modeling of Hardware in SoC Design

- Register Transfer Level (RTL) Modeling
 - Block diagram of generic RTL component (low level)



Source:
<http://www.eda.org/alc-cwg/cwg-open.pdf>

Modeling of Hardware in SoC Design

- RTL Modeling
 - State modeling: *Accellera RTL Semantics Standard*
 - Style 1: *unmapped*
 - `a = b * c;`
 - Style 2: *storage mapped*
 - `R1 = R1 * RF2[4];`
 - Style 3: *function mapped*
 - `R1 = ALU1(MULT, R1, RF2[4]);`
 - Style 4: *connection mapped*
 - `Bus1 = R1;`
 - `Bus2 = RF2[4];`
 - `Bus3 = ALU1(MULT, Bus1, Bus2);`
 - Style 5: *exposed control*
 - `ALU_CTRL = 011001b;`
 - `RF2_CTRL = 010b;`
 - ...

Source: <http://www.eda.org/alc-cwg/cwg-open.pdf>

The SpecC Language

- RTL Modeling
 - Types specific to RTL
 - `bit[1:r]` two-value logic vector of arbitrary length
 - `bit4[1:r]` four-value logic vector of arbitrary length
 - Type modifiers specific to RTL
 - `buffered` Storage
 - `signal` Communication
 - Control flow specific to RTL
 - `fsmd` Explicit finite state machine with datapath

The SpecC Language

- Bit vector type: **bit**
 - signed or unsigned
 - arbitrary length
 - standard operators
 - logical operations
 - arithmetic operations
 - comparison operations
 - type conversion
 - type promotion
 - concatenation operator
 - a @ b
 - slice operator
 - a[l:r]

```
typedef bit[7:0] byte; // type definition
byte a;
unsigned bit[16] b;

bit[31:0] BitMagic(bit[4] c, bit[32] d)
{
    bit[31:0] r;

    a = 11001100b; // constant
    b = 1111000011110000ub; // assignment

    b[7:0] = a; // sliced access
    b = d[31:16];

    if (b[15]) // single bit
        b[15] = 0b; // access

    r = a @ d[11:0] @ c // concatenation
        @ 11110000b;

    a = ~(a & 11110000); // logical op.
    r += 42 + 3*a; // arithmetic op.

    return r;
}
```

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The SpecC Language

- Four-value bit vector type: **bit4**
 - 4-value logic
 - 1 (0q1) high
 - 0 (0q0) low
 - x (0qx) unknown
 - z (0qz) high impedance
 - signed or unsigned
 - arbitrary length
 - standard operators
 - same as for regular bit vectors
 - resolution function
 - type modifier **resolved**

```
bit4[31:0] BitMagic(bit4[4] a, bit4[32] b)
{
    resolved bit4[31:0] r;

    a = 0q11001100;
    b = 0q11110000zzzzxxxx;
    r = 0xq01XZ;

    return r;
}
```

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The SpecC Language

- **buffered** type modifier
 - Representation of storage in RTL models
 - register
 - register file
 - memory
 - Update at notification of specified events
 - synchronized with explicit clock

```

event Clk1, Clk2;           // system clock
buffered[Clk1] bit[32] R1;  // register
buffered[Clk1] bit[32] R2;

buffered[CLK2] bit[16] RF[64]; // register file
buffered[CLK2] bit[ 8] M[1024]; // memory

R1 = R2;           // swap contents of R1 and R2
R2 = R1;
wait CLK1;

RF[2] = RF[0] + RF[1];
...
wait CLK2;
    
```

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The SpecC Language

- **signal** type modifier
 - Representation of wires and busses in RTL models
 - Semantics as in VHDL, Verilog

```

signal bit[31:0] addr; // address bus
signal bit[31:0] data; // data bus
buffered[CLK] M[1024];

wait addr;           // memory read access
data = M[addr];
...

wait addr && data;
M[addr] = data;     // memory write access
...
    
```

- Implemented as buffered variables with associated event

```

signal int x;      ⇔ buffered int x_v; event x_e;
x = 55;           ⇔ x_v = 55; notify x_e;
y = x + 2;        ⇔ y = x_v + 2;
wait x;           ⇔ wait x_e;
notify x;         ⇔ notify x_e;
    
```

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The SpecC Language

- RTL control flow
 - **fsmd** construct
 - Similar to **fsm** construct, but specifically for RTL
 - Explicit states and state transitions
 - State actions represent well-defined register transfers
 - limited to conditional/unconditional assignments and function calls
 - general loops, exceptions, synchronization, timing are not allowed
 - Explicit clock specifier
 - event list (external clock)
 - time delay (internal clock)
 - Explicit sensitivity list
 - needed for Mealy machine support
 - Explicit reset state
 - synchronous reset
 - asynchronous reset

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The SpecC Language

RTL
Modeling
Example

```
behavior FSMD_Example(
    signal in bool    CLK,           // system clock
    signal in bool    RST,           // system reset
    signal in bit[31:0] Inport,      // input ports
    signal in bit[1]   Start,        //
    signal out bit[31:0] Outport,     // output ports
    signal out bit[1]   Done)
{
    void main(void)
    {
        fsmd(CLK)                   // clock + sensitivity
        {
            bit[32] a, b, c, d, e;    // local variables

            { Outport = 0;           // default
              Done = 0b;            // assignments
            }

            if (RST) { goto S0;      // reset actions
            }

            S0 : { if (Start) goto S1;
                  else      goto S0;
            }

            S1 : { a = b + c;         // state actions
                  d = Inport * e;    // (register transfers)
                  Outport = a;
                  goto S2;
            }

            ... }
        }
    };
};
```

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The SpecC Language

RTL
Modeling
Example

```
behavior FSMD_Example(
  signal in bool    CLK,           // system clock
  signal in bool    RST,           // system reset
  signal in bit[31:0] Inport,      // input ports
  signal in bit[1]   Start,
  signal out bit[31:0] Outport,    // output ports
  signal out bit[1]   Done)
{
  void main(void)
  {
    fsmd(CLK)                       // clock + sensitivity
    {
      bit[32] a, b, c, d, e;         // local variables

      { Outport = 0;                 // default
        Done = 0b;                  // assignments
      }

      if (RST) { goto S0;           // reset actions
      }

      S0 : { if (Start) goto S1;
            else      goto S0;
          }

      S1 : { a = b + c;              // state actions
            d = Inport * e;         // (register transfers)
            Outport = a;
            goto S2;
          }

      ... }
    }
  };
};
```

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The SpecC Language

RTL
Modeling
Example

```
behavior FSMD_Example(
  signal in bool    CLK,           // system clock
  signal in bool    RST,           // system reset
  signal in bit[31:0] Inport,      // input ports
  signal in bit[1]   Start,
  signal out bit[31:0] Outport,    // output ports
  signal out bit[1]   Done)
{
  void main(void)
  {
    fsmd(CLK; Inport, Start)        // clock + sensitivity
    {
      bit[32] a, b, c, d, e;         // local variables

      { Outport = 0;                 // default
        Done = 0b;                  // assignments
      }

      if (RST) { goto S0;           // reset actions
      }

      S0 : { if (Start) goto S1;
            else      goto S0;
          }

      S1 : { a = b + c;              // state actions
            d = Inport * e;         // (register transfers)
            Outport = a;
            goto S2;
          }

      ... }
    }
  };
};
```

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The SpecC Language

RTL
Modeling
Example

```

behavior FSMD_Example(
  signal in bool    CLK,          // system clock
  signal in bool    RST,          // system reset
  signal in bit[31:0] Inport,     // input ports
  signal in bit[1]  Start,        //
  signal out bit[31:0] Outport,   // output ports
  signal out bit[1]  Done)
{
  void main(void)
  {
    fsmd(CLK; RST)                // asynchronous reset
    {
      bit[32] a, b, c, d, e;      // local variables
      { Outport = 0;              // default
        Done = 0b;               // assignments
      }

      if (RST) { goto S0;        // reset actions
    }
    S0 : { if (Start) goto S1;
           else      goto S0;
        }
    S1 : { a = b + c;             // state actions
           d = Inport * e;       // (register transfers)
           Outport = a;
           goto S2;
        }
    ... }
  }
};

```

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The SpecC Language

RTL
Modeling
Example

```

behavior FSMD_Example(
  signal in bool    CLK,          // system clock
  signal in bool    RST,          // system reset
  signal in bit[31:0] Inport,     // input ports
  signal in bit[1]  Start,        //
  signal out bit[31:0] Outport,   // output ports
  signal out bit[1]  Done)
{
  void main(void)
  {
    fsmd(CLK)                    // clock + sensitivity
    {
      bit[32] a, b, c, d, e;      // local variables
      { Outport = 0;              // default
        Done = 0b;               // assignments
      }
      if (RST) { goto S0;        // reset actions
    }
    S0 : { if (Start) goto S1;
           else      goto S0;
        }
    S1 : { a = b + c;             // state actions
           d = Inport * e;       // (register transfers)
           Outport = a;
           goto S2;
        }
    ... }
  }
};

```

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The SpecC Language

RTL
Modeling
Example

```
behavior FSMD_Example(
  signal in bool    CLK,          // system clock
  signal in bool    RST,          // system reset
  signal in bit[31:0] Inport,     // input ports
  signal in bit[1]  Start,        //
  signal out bit[31:0] Outport,   // output ports
  signal out bit[1]  Done)
{
  void main(void)
  {
    fsmd(CLK)                    // clock + sensitivity
    {
      bit[32] a, b, c, d, e;      // local variables

      { Outport = 0;              // default
        Done = 0b;                // assignments
      }

      if (RST) { goto S0;         // reset actions

      S0 : { if (Start) goto S1;
            else goto S0;
          }

      S1 : { a = b + c;            // state actions
            d = Inport * e;       // (register transfers)
            Outport = a;
            goto S2;
          }

      ... }
    }
  };
};
```

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The SpecC Language

RTL
Modeling
Example

```
behavior FSMD_Example(
  signal in bool    CLK,          // system clock
  signal in bool    RST,          // system reset
  signal in bit[31:0] Inport,     // input ports
  signal in bit[1]  Start,        //
  signal out bit[31:0] Outport,   // output ports
  signal out bit[1]  Done)
{
  void main(void)
  {
    fsmd(CLK)                    // clock + sensitivity
    {
      bit[32] a, b, c, d, e;      // local variables

      { Outport = 0;              // default
        Done = 0b;                // assignments
      }

      if (RST) { goto S0;         // reset actions

      S0 : { if (Start) goto S1;
            else goto S0;
          }

      S1 : { a = b + c;            // state actions
            d = Inport * e;       // (register transfers)
            Outport = a;
            goto S2;
          }

      ... }
    }
  };
};
```

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The SpecC Language

RTL
Modeling
Example

```

behavior FSMD_Example(
  signal in bool      CLK,          // system clock
  signal in bool      RST,          // system reset
  signal in bit[31:0] Inport,       // input ports
  signal in bit[1]    Start,        //
  signal out bit[31:0] Outport,     // output ports
  signal out bit[1]   Done)
{
  void main(void)
  {
    fsmd(CLK)                       // clock + sensitivity
    {
      bit[32] a, b, c, d, e;         // unmapped variables

      { Outport = 0;                 // default
        Done = 0b;                   // assignments
      }

      if (RST) { goto S0;            // reset actions
      }

      S0 : { if (Start) goto S1;
            else      goto S0;
          }

      S1 : { a = b + c;               // Accellera style 1
            d = Inport * e;          // (unmapped)
            Outport = a;
            goto S2;
          }

      ...
    }
  }
};

```

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The SpecC Language

RTL
Modeling
Example

```

behavior FSMD_Example(
  signal in bool      CLK,          // system clock
  signal in bool      RST,          // system reset
  signal in bit[31:0] Inport,       // input ports
  signal in bit[1]    Start,        //
  signal out bit[31:0] Outport,     // output ports
  signal out bit[1]   Done)
{
  void main(void)
  {
    fsmd(CLK)                       // clock + sensitivity
    {
      buffered[CLK] bit[32] RF[4];   // register file

      { Outport = 0;                 // default
        Done = 0b;                   // assignments
      }

      if (RST) { goto S0;            // reset actions
      }

      S0 : { if (Start) goto S1;
            else      goto S0;
          }

      S1 : { RF[0]=RF[1]+RF[2];       // Accellera style 2
            RF[3]=Inport*RF[4];      // (storage mapped)
            Outport = RF[0];
            goto S2;
          }

      ...
    }
  }
};

```

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The SpecC Language

RTL
Modeling
Example

```
behavior FSMExample(
  signal in bool    CLK,          // system clock
  signal in bool    RST,          // system reset
  signal in bit[31:0] Inport,     // input ports
  signal in bit[1]  Start,        // Start
  signal out bit[31:0] Outport,   // output ports
  signal out bit[1]  Done)
{
  void main(void)
  {
    fsmd(CLK) // clock + sensitivity
    {
      buffered[CLK] bit[32] RF[4]; // register file
      {
        Outport = 0; // default
        Done = 0b; // assignments
      }
      if (RST) { goto S0; // reset actions
      }
      S0 : { if (Start) goto S1;
            else goto S0;
          }
      S1 : { RF[0] = // Accellera style 3
            ADD0(RF[1],RF[2]); // (function mapped)
            RF[3] =
            MUL0(Inport,RF[4]);
            Outport = RF[0];
            goto S2;
          }
    }
  }
};
```

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The SpecC Language

RTL
Modeling
Example

```
behavior FSMExample(
  signal in bool    CLK,          // system clock
  signal in bool    RST,          // system reset
  signal in bit[31:0] Inport,     // input ports
  signal in bit[1]  Start,        // Start
  signal out bit[31:0] Outport,   // output ports
  signal out bit[1]  Done)
{
  void main(void)
  {
    fsmd(CLK) // clock + sensitivity
    {
      buffered[CLK] bit[32] RF[4]; // register file
      bit[32] BUS0, BUS1, BUS2; // busses
      {
        Outport = 0; // default
        Done = 0b; // assignments
      }
      if (RST) { goto S0; // reset actions
      }
      S0 : { if (Start) goto S1;
            else goto S0;
          }
      S1 : { BUS0 = RF[1]; // Accellera style 4
            BUS1 = RF[2]; // (connection mapped)
            BUS3 = ADD0(BUS0,BUS1);
            RF[0] = BUS3;
            ...
            goto S2;
          }
    }
  }
};
```

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The SpecC Language

RTL
Modeling
Example

```
behavior FSMD_Example(
  signal in bool    CLK,          // system clock
  signal in bool    RST,          // system reset
  signal in bit[31:0] Inport,     // input ports
  signal in bit[1]  Start,        // Start
  signal out bit[31:0] Outport,   // output ports
  signal out bit[1]  Done)
{
  void main(void)
  {
    fsmd(CLK)                    // clock + sensitivity
    {
      signal bit[5:0] RF_CTRL;    // control wires
      signal bit[1:0] ADD0_CTRL, MULO_CTRL;

      { Outport = 0;              // default
        Done = 0b;                // assignments
      }

      if (RST) { goto S0;         // reset actions
    }

    S0 : { if (Start) goto S1;
          else goto S0;
        }

    S1 : { RF_CTRL = 011000b;    // Accellera style 5
          ADD0_CTRL = 01b;      // (exposed control)
          MULO_CTRL = 11b;
          ...
          goto S2;
        }
    }
  };
};
```

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Homework Assignment 5

- Tasks
 - Creating behaviors in C code
 - converting statement sequences into behaviors
 - Pointer elimination
 - replace pointers by their actual references
 - See posted detailed instructions!

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Homework Assignment 5

- Deliverables
 - 1-paragraph description about the two tasks
 - How far did you get?
 - What were the problems?
 - How did you solve it?
 - Report the time stamps
 - How long did it take to do the tasks?
- Due
 - Week 8 (next week)