# **Chapter 5: CPU Scheduling**



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# **Chapter 5: CPU Scheduling**

- Basic Concepts
- Scheduling Criteria
- Scheduling Algorithms
- Thread Scheduling
- Multiple-Processor Scheduling
- Operating Systems Examples
- Algorithm Evaluation



### **Objectives**

- To introduce CPU scheduling, which is the basis for multi-programmed operating systems
- To describe various CPU-scheduling algorithms
- To discuss evaluation criteria for selecting a CPU-scheduling algorithm for a particular system

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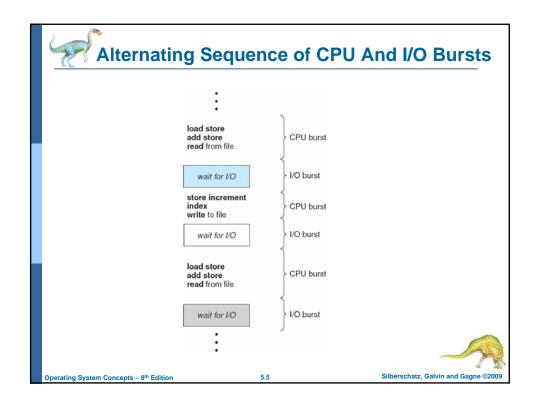
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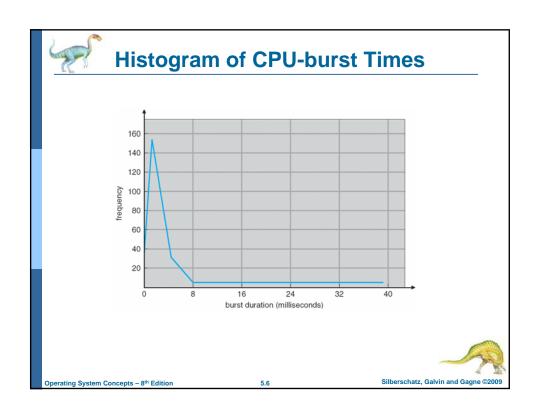
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#### **Basic Concepts**

- Maximum CPU utilization obtained with multiprogramming
- CPU-I/O Burst Cycle –
  Process execution consists of a cycle of
  - CPU execution and
  - I/O wait
- CPU burst distribution







#### **CPU Scheduler**

- Selects from among the processes in memory that are ready to execute, and allocates the CPU to one of them
- CPU scheduling decisions may take place when a process:
  - 1. Switches from running to waiting state
  - 2. Switches from running to ready state
  - 3. Switches from waiting to ready
  - 4. Terminates
- Scheduling under 1 and 4 is non-preemptive
- All other scheduling is preemptive

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#### **Dispatcher**

- Dispatcher module gives control of the CPU to the process selected by the short-term scheduler
- Dispatching involves:
  - switching context
  - switching to user mode
  - jumping to the proper location in the user program to restart that program
- Dispatch latency
  - time it takes for the dispatcher to stop one process and start another running



#### **Scheduling Algorithm Criteria**

- CPU utilization
  - keep the CPU as busy as possible
- Throughput
  - number of processes that complete their execution per time unit
- Turnaround time
  - · amount of time to execute a particular process
- Waiting time
  - amount of time a process has been waiting in the ready queue
- Response time
  - amount of time it takes from when a request was submitted until the first response is produced (not the time to output result!)
  - · for time-sharing environment

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# Scheduling Algorithm *Optimization* Criteria

- Maximize CPU utilization
  - · keep the CPU as busy as possible
- Maximize Throughput
  - number of processes that complete their execution per time unit
- Minimize Turnaround time
  - · amount of time to execute a particular process
- Minimize Waiting time
  - amount of time a process has been waiting in the ready queue
- Minimize Response time
  - amount of time it takes from when a request was submitted until the first response is produced (not the time to output result!)
  - · for time-sharing environment



<b>Process</b>	Burst Time	
$P_1$	24	
$P_2$	3	
$P_3$	3	

 $\blacksquare$  Suppose that the processes arrive in the order:  $P_{\rm 1}$  ,  $P_{\rm 2}$  ,  $P_{\rm 3}$  The Gantt Chart for the schedule is:



- Waiting time for  $P_1 = 0$ ;  $P_2 = 24$ ;  $P_3 = 27$
- Average waiting time: (0 + 24 + 27)/3 = 17



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#### **FCFS Scheduling (Cont)**

Suppose that the processes arrive in the order

$$P_2, P_2, P_3$$

■ The Gantt chart for the schedule is:



- Waiting time for  $P_1 = 6$ ;  $P_2 = 0$ .  $P_3 = 3$
- Average waiting time: (6 + 0 + 3)/3 = 3
- Much better than previous case
- Convoy effect short process behind long process





- Associate with each process the length of its next CPU burst.
- Use these lengths to schedule the process with the shortest time.
- SJF is optimal
  - SJF gives minimum average waiting time for a given set of processes
- However, there's a problem:
  - The difficulty is knowing the length of the next CPU request...

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#### **Example of SJF**

<u>Process</u>	Burst Time
$P_1$	6
$P_2$	8
$P_3$	7
$P_4$	3

SJF scheduling chart



Average waiting time = (3 + 16 + 9 + 0) / 4 = 7

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# **Estimating Length of Next CPU Burst**

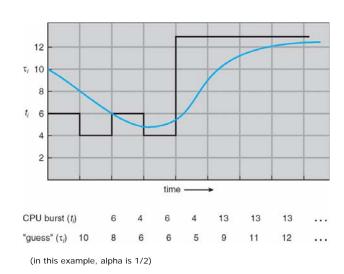
- Can only estimate the length!
  - Note: Text book calls this estimation prediction.
- Can be done by using the length of previous CPU bursts
  - using exponential averaging
    - 1.  $t_n = \text{actual length of } n^{th} \text{ CPU burst}$
    - 2.  $\tau_{n+1}$  = predicted value for the next CPU burst
    - 3.  $\alpha$ ,  $0 \le \alpha \le 1$
    - 4. Define:  $\tau_{n+1} = \alpha t_n + (1-\alpha)\tau_n$



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# Estimating the Length of the Next CPU Burst



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$$\tau_{n+1} = \alpha t_n + (1 - \alpha)\tau_n$$

- α =0
  - $\bullet \quad \tau_{n+1} = \tau_n$
  - · Recent history does not count
- $\alpha = 1$ 
  - $\tau_{n+1} = \alpha t_n$
  - Only the actual last CPU burst counts
- If we expand the formula, we get:

$$\begin{split} \tau_{n+1} &= \alpha \ t_n + (1 - \alpha) \alpha \ t_{n-1} + \dots \\ &+ (1 - \alpha)^j \alpha \ t_{n-j} + \dots \\ &+ (1 - \alpha)^{n+1} \tau_0 \end{split}$$

 Since both α and (1 - α) are less than or equal to 1, each successive term has less weight than its predecessor

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#### **Priority Scheduling**

- A priority number (an integer) is associated with each process
- The CPU is allocated to the process with the highest priority (smallest integer = highest priority)
  - Preemptive
  - Non-preemptive
- SJF is an example of priority scheduling where priority is the predicted next CPU burst time
- Problem = Starvation
  - low priority processes may never execute
- Solution = Aging
  - as time progresses, increase the priority of the process



#### Round Robin (RR) Scheduling

- Each process gets a small unit of CPU time (*time quantum*), usually 10-100 milliseconds.
- After this time has elapsed, the process is preempted and added to the end of the ready queue.
- If there are *n* processes in the ready queue and the time quantum is *q*, then each process gets 1/*n* of the CPU time in chunks of at most *q* time units at once.
- No process waits more than (n-1)q time units.
- Performance
  - q large ⇒ RR degenerates to FCFS
  - q small ⇒ q should be large with respect to context switch, otherwise overhead is too high

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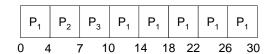
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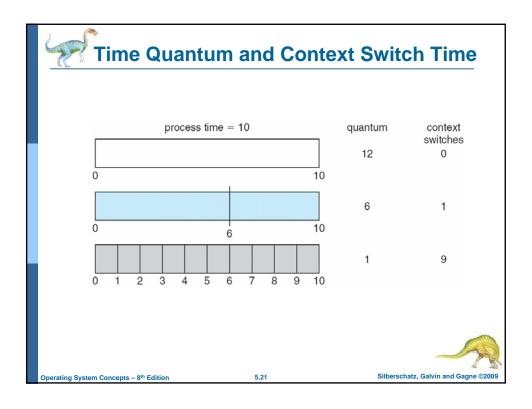
# Example of RR with Time Quantum = 4

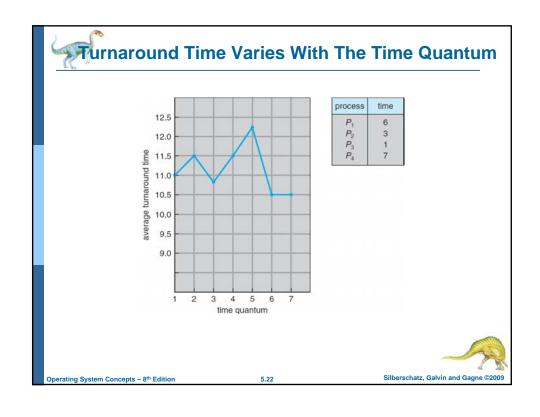
<u>Process</u>	Burst Time
$P_1$	24
$P_2$	3
$P_3$	3

■ The Gantt chart is:



■ Typically, higher average *turnaround* than SJF, but better *response* 







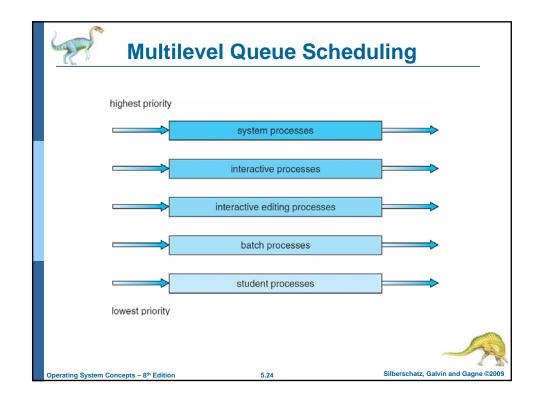
#### **Multilevel Queue Scheduling**

- Ready queue is partitioned into separate queues
  - foreground (interactive)
  - background (batch)
- Each queue has its own scheduling algorithm
  - foreground RR
  - background FCFS
- Scheduling must be done between the queues
  - Fixed priority scheduling
    - i.e., serve all from foreground then from background
    - Possibility of starvation.
  - Time slice
    - each queue gets a certain amount of CPU time which it can schedule amongst its processes
      - i.e., 80% to foreground in RR
      - 20% to background in FCFS

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#### **Multilevel Feedback Queue**

- A process can move between the various queues
  - aging can be implemented this way
- Multilevel-feedback-queue scheduler is defined by the following parameters:
  - number of queues
  - · scheduling algorithms for each queue
  - method used to determine when to upgrade a process
  - method used to determine when to demote a process
  - method used to determine which queue a process will enter when that process needs service

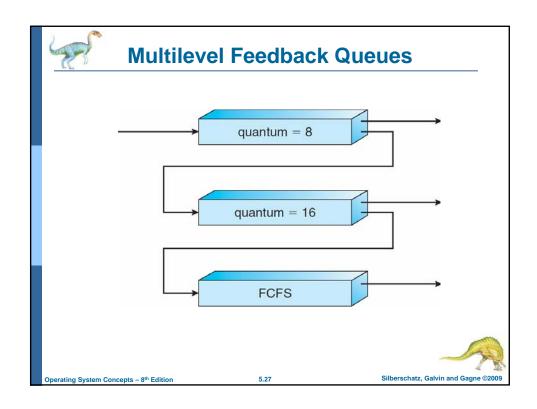
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# **Example of Multilevel Feedback Queue**

- Three queues:
  - Q<sub>0</sub> time quantum 8 milliseconds
  - Q<sub>1</sub> time quantum 16 milliseconds
  - Q<sub>2</sub> FCFS
- Scheduling
  - A new job enters queue Q<sub>0</sub> which is scheduled FCFS.
  - When it gains CPU, job receives 8 milliseconds.
  - If it does not finish in 8 milliseconds, job is moved to queue Q1.
  - At Q<sub>1</sub> job is again scheduled FCFS and receives 16 additional milliseconds.
  - If it still does not complete, it is preempted and moved to queue Q<sub>2</sub>.





#### **Thread Scheduling**

- Distinction between *user-level* and *kernel-level* threads
- With many-to-one and many-to-many models, thread library schedules user-level threads to run on light-weight processes (LWP)
  - Known as process-contention scope (PCS) since scheduling competition is within the process
- Kernel thread scheduled onto available CPU is system-contention scope (SCS)
  - competition among all threads in system



#### **Pthread Scheduling API**

- POSIX API allows specifying either PCS or SCS as thread attribute
  - PTHREAD\_SCOPE\_PROCESS schedules threads using PCS scheduling
  - PTHREAD\_SCOPE\_SYSTEM schedules threads using SCS scheduling
- Contention scope can be obtained using
  - pthread\_attr\_getscope(&attr, &scope)
- Contention scope can be set using
  - pthread\_attr\_setscope(&attr, PTHREAD\_SCOPE\_PROCESS)
  - pthread\_attr\_setscope(&attr, PTHREAD\_SCOPE\_SYSTEM)



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#### **Pthread Scheduling API**

```
#include <pthread.h>
#include <stdio.h>
#define NUM THREADS 5
int main(int argc, char *argv[])
   int i;
   pthread_t tid[NUM THREADS];
   pthread_attr_t attr;
   /* get the default attributes */
   pthread_attr_init(&attr);
   /* set the scheduling algorithm to PROCESS or SYSTEM */
   pthread_attr_setscope(&attr, PTHREAD_SCOPE_SYSTEM);
   /* set the scheduling policy - FIFO, RR, or OTHER */
   pthread_attr_setschedpolicy(&attr, SCHED_OTHER);
   /* create the threads */
   for (i = 0; i < NUM_THREADS; i++)
        pthread_create(&tid[i],&attr,runner,NULL);
```

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```
/* now join on each thread */
for (i = 0; i < NUM THREADS; i++)
    pthread_join(tid[i], NULL);
}

/* Each thread will begin control in this function */
void *runner(void *param)
{
    printf("I am a thread\n");
    pthread_exit(0);
}</pre>
```

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#### **Multiple-Processor Scheduling**

- CPU scheduling more complex when multiple CPUs are available
- Homogeneous processors within a multiprocessor
- Asymmetric multiprocessing
  - only one processor accesses the system data structures, alleviating the need for data sharing
- Symmetric multiprocessing (SMP)
  - · each processor is self-scheduling
  - all processes in common ready queue, or each has its own private queue of ready processes
- Processor affinity –

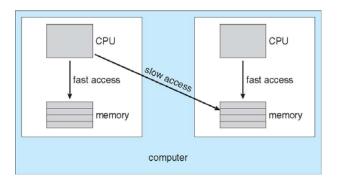
process has affinity for processor(s) on which it is currently running

- soft affinity: process should run on specified processor(s)
- hard affinity: process must only run on specified processor(s)



# **NUMA and Processor Affinity**

- Non-Uniform Memory Access (NUMA)
  - · A CPU has faster access to some memory than to others

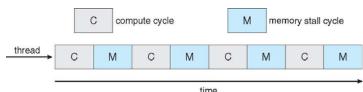


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- Recent trend to place multiple processor cores on same physical chip
  - Typically faster, consumes less power than single-core architecture
- Also, multiple threads per core growing ("hyper-threading")
  - Takes advantage of memory stall to make progress on another thread while memory retrieve happens
  - Example:



time

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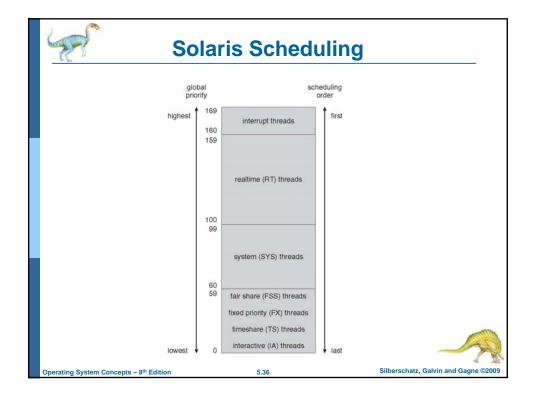
# **Operating System Examples**

- Solaris scheduling
- Windows XP scheduling
- Linux scheduling

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### **Solaris Dispatch Table**

priority	time quantum	time quantum expired	return from sleep
0	200	0	50
5	200	0	50
10	160	0	51
15	160	5	51
20	120	10	52
25	120	15	52
30	80	20	53
35	80	25	54
40	40	30	55
45	40	35	56
50	40	40	58
55	40	45	58
59	20	49	59

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#### **Algorithm Evaluation**

- Deterministic modeling
  - takes a particular predetermined workload and defines the performance of each algorithm for that workload
  - this has been done in this chapter for the algorithms in the beginning
  - Advantages: simple, fast, exact
  - Disadvantages: specific case only
- Queueing models
  - [skipped]
- Simulation
  - see next slide
- Implementation
  - Real evaluation, but expensive...

